# A consensus-based global optimization method for high dimensional machine learning problems 

## Yuhua Zhu

Joint work with Jose Carrilo, Shi Jin, Lei Li
Oct 22, 2019

## Motivations



Numerical experiments


## The Model and algorithm

## Numerical experiments

$$
\text { Goal: find } x^{*}=\operatorname{argmin}_{x} L(x), L(x) \text { is a non-convex function. }
$$

$$
\text { For example: } L(x)=\frac{1}{n} \sum_{i} l_{i}(x)
$$

## Why non-gradient method?

- Gradient is hard to calculate
- Objective function is non-smooth
- Flat local minimum


It is hard for gradient based method to escape from flat local minimum

$$
\begin{gathered}
\text { GD: } X^{\prime}(t)=-\nabla L(X(t)) \\
\text { SGD: } d X_{t}=-\nabla L\left(X_{t}\right)+\sqrt{\frac{1}{\beta}} d B_{t} \\
\text { p.d.f of SGD: } \partial_{t} p(t, x)=\nabla \cdot\left[\nabla L(x) p+\frac{2}{\beta} \nabla p\right] \\
p^{\infty}(x)=\frac{1}{Z} e^{-\frac{\beta}{2} L(x)}
\end{gathered}
$$

[Z-Dai, 18], [Jastrzebski-Bengio, 18]

$$
\frac{\mathbb{P}\left(\text { converge to } X^{1}\right)}{\mathbb{P}\left(\text { converge to } X^{2}\right)}=\sqrt{\frac{\operatorname{det} H_{2}}{\operatorname{det} H_{1}}} e^{\frac{\beta}{2}\left(L_{2}-L_{1}\right)}
$$

When $\frac{\sqrt{\operatorname{det} H_{1}}}{\sqrt{\operatorname{det} H_{2}}}<\frac{e^{\frac{\beta}{2} L_{1}}}{e^{\frac{\beta}{2} L_{2}}}$, SGD is more likely to converge to the flat local minimum.

It is hard for gradient based method to escape from flat local minimum

Example:

$$
\begin{aligned}
& \ell\left(x, \hat{x}_{i}\right)=e^{\sin \left(2 x^{2}\right)}+\frac{1}{10}\left(x-\hat{x}_{i}-\frac{\pi}{2}\right)^{2}, \quad \hat{x}_{i} \sim N(0,0.1) \\
& L(x)=\frac{1}{n} \sum_{i} \ell\left(x, \hat{x}_{i}\right)
\end{aligned}
$$



Success rate for SGD to find the correct global minimum is 18\%

## Motivations



## Numerical experiments

## Related Work [Pinnau-Totzeck-Tse-Martin, 17]



For $j=1, \cdots, N$
$d X^{j}=-\lambda\left(X^{j}-\bar{x}^{*}\right) H^{\epsilon}\left(L\left(X^{j}\right)-L\left(\bar{x}^{*}\right)\right) d t+\sigma\left|X^{j}-\bar{x}^{*}\right| d W^{j}$
where $\bar{x}^{*}=\frac{1}{\sum_{j=1}^{N} e^{-\beta L\left(X^{j}\right)}} \sum_{j=1}^{N} X^{j} e^{-\beta L\left(X^{j}\right)}$.

Relax to their weighted average, in the meantime, explore their surrounding environment.

Require $\lambda \sim O(d)$ to guarantee the convergence of the method

## First improvement

$$
d X^{j}=-\lambda\left(X^{j}-\bar{x}^{*}\right) d t+\sigma \sum_{k=1}^{d}\left(X^{j}-\bar{x}^{*}\right)_{k} d W_{k}^{j} \vec{e}_{k}
$$

component-wise geometric Brownian motion

- Intuitively, now the diffusivity allows the particles to explore each dimension with different rate, so more possible to find the global minimum.

Assume $x^{*}=a$ is a constant.

$$
d X=-\lambda(X-a) d t+\sigma|X-a| d W^{j}
$$

For each dimension $\mathbf{i}$


By Ito's formula and then take expectation
$d \mathbb{E}\left[(X)_{i}-(a)_{i}\right]^{2}=-2 \lambda \mathbb{E}\left[(X)_{i}-(a)_{i}\right]^{2} d t+\sigma^{2} \mathbb{E}|X-a|^{2} d t$
Sum over all dimension
$\frac{d}{d t} \mathbb{E}|X-a|^{2}=-2 \lambda \mathbb{E}|X-a|^{2}+\sigma^{2} \sum_{i=1}^{d} \mathbb{E}|X-a|^{2}=\left(-2 \lambda+\sigma^{2} d\right) \mathbb{E}|X-a|^{2}$
$2 \lambda>d \sigma^{2}$


$$
d\left[(X)_{i}-(a)_{i}\right]=-\lambda\left[(X)_{i}-(a)_{i}\right] d t+\sigma\left[(X)_{i}-(a)_{i}\right] d\left(W^{j}\right)_{i}
$$


$d \mathbb{E}\left[(X)_{i}-(a)_{i}\right]^{2}=-2 \lambda \mathbb{E}\left[(X)_{i}-(a)_{i}\right]^{2} d t+\sigma^{2}\left[(X)_{i}-(a)_{i}\right]^{2} d t$

$2 \lambda>\sigma^{2}$
[Carrillo-Choi-Totzeck-Tse, 18]

## Mean field limit of the continuous model

$$
\begin{gathered}
d X^{j}=-\lambda\left(X^{j}-\bar{x}^{*}\right) d t+\sigma \sum_{k=1}^{d}\left(X^{j}-\bar{x}^{*}\right)_{k} d W_{k}^{j} \vec{e}_{k} \\
\downarrow N \rightarrow \infty \\
d X=-\lambda\left(X-X^{*}\right) d t+\sigma \sum_{i=1}^{d} \vec{e}_{i}\left(X-X^{*}\right)_{i} d W_{i} \\
\text { with } X^{*}=\frac{\mathbb{E}\left(X e^{-\beta L(X)}\right)}{\mathbb{E}\left(e^{-\beta L(X)}\right)} .
\end{gathered}
$$

## Theorem: [Carrilo-Jin-Li-Z, 19]

Under some condition on the initial distribution of $X$ and $\lambda, \sigma, X(t) \rightarrow \tilde{x}$ exponentially fast and,

$$
L(\tilde{x}) \leq-\frac{1}{\beta} \log \mathbb{E} e^{-\beta L(X(0))}+\frac{\log 2}{\beta} \leq L\left(x^{*}\right)+O\left(\beta^{-1}\right)
$$

The initial law of $X$

## Numerical method

## A gradient-free optimization method

Goal: find $x^{*}=\operatorname{argmin}_{x} L(x)=\operatorname{argmin}_{x} \frac{1}{n} \sum_{i} l_{i}(x)$

## Algorithm [Carrillo-Jin-Li-Z-19]

Initially, randomly generate $N$ particles $X^{j}$, at each step we randomly update $M$ particles.



- Find a weighted average: $\bar{X}^{*}=\frac{1}{\sum_{j=1}^{N} \mu^{j}} \sum_{j=1}^{N} X^{j} \mu^{j}, \mu^{j}=e^{-\beta E(\mathbf{x})}$
- Let $X^{j}$ move towards $X^{*}$ and and explore their neighbor at the same time.

$$
X^{j} \leftarrow X^{j}-\lambda \gamma\left(X^{j}-\bar{X}^{*}\right)+\sigma \sqrt{\gamma} \sum_{i=1}^{d} \vec{e}_{i}\left(X^{j}-\bar{X}^{*}\right)_{i} z_{i}, \quad z_{i} \sim \mathcal{N}(0,1)
$$

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Example:

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& L(x)=\frac{1}{n} \sum_{i} \ell\left(x, \hat{x}_{i}\right)
\end{aligned}
$$



Success rate of our method is $98 \%$ !
(with $N=100, M=20$ )

$$
L(x)=\frac{1}{d} \sum_{i=1}^{d}\left[\left(x_{i}-B\right)^{2}-10 \cos \left(2 \pi\left(x_{i}-B\right)\right)+10\right]+C
$$



Rastrigin function in $d=20$ with $\beta=30$

TABLE 2. Rastrigin function in $d=20$ with $\alpha=30$.

|  |  | $N$ |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $x_{*}$ |  | 50 | 100 | 200 |
| 0 | success rate | $34 . \%$ | $61.1 \%$ | $62.2 \%$ |
|  | $\frac{1}{d} \mathbb{E}\left[\left\\|v_{f}(T)-x_{*}\right\\|^{2}\right]$ | $3.12 e^{-1}$ | $2.47 e^{-1}$ | $2.42 e^{-1}$ |
| 1 | success rate | $34.5 \%$ | $57.1 \%$ | $61.6 \%$ |
|  | $\frac{1}{d} \mathbb{E}\left[\left\\|v_{f}(T)-x_{*}\right\\|^{2}\right]$ | $3.09 e^{-1}$ | $2.52 e^{-1}$ | $0.244 e^{-1}$ |
| 2 | success rate | $35.5 \%$ | $54.8 \%$ | $62.4 \%$ |
|  | $\frac{1}{d} \mathbb{E}\left[\left\\|v_{f}(T)-x_{*}\right\\|^{2}\right]$ | $3.06 e^{-1}$ | $2.51 e^{-1}$ | $2.44 e^{-1}$ |

[Pinnau-Totzeck-Tse-Martin, 17]

|  | $\mathrm{N}=50, \mathrm{M}=40$ <br> $\sigma=5.1$ | $\mathrm{N}=100, \mathrm{M}=70$ <br> $\sigma=5.1$ | $\mathrm{N}=200, \mathrm{M}=100$ <br> $\sigma=5.1$ |
| :--- | ---: | ---: | ---: |
| $\mathbf{x}^{*}=0$, success rate | $97 \%$ | $99 \%$ | $98 \%$ |
| $\mathbf{x}^{*}=0, \quad \frac{1}{d} \mathbb{E}\left[\left\\|x_{T}^{*}-x^{*}\right\\|^{2}\right]$ | $5.6 \mathrm{E}-03$ | $5.03 \mathrm{E}-04$ | $9.71 \mathrm{E}-04$ |
| $\mathbf{x}^{*}=1$, success rate | $94 \%$ | $99 \%$ | $95 \%$ |
| $\mathbf{x}^{*}=1, \quad \frac{1}{d} \mathbb{E}\left[\left\\|x_{T}^{*}-x^{*}\right\\|^{2}\right]$ | $3.9 \mathrm{E}-03$ | $4.95 \mathrm{E}-04$ | $3 \mathrm{E}-03$ |
| $\mathbf{x}^{*}=2$, success rate | $97 \%$ | $100 \%$ | $92 \%$ |
| $\mathbf{x}^{*}=2, \frac{1}{d} \mathbb{E}\left[\left\\|x_{T}^{*}-x^{*}\right\\|^{2}\right]$ | $3.0 \mathrm{E}-03$ | $8.06 \mathrm{E}-06$ | $4 \mathrm{E}-03$ |
| Computing time saved | $22.03 \%$ | $30.11 \%$ | $36.14 \%$ |

## Learning MNIST data with two layer Neural Network

$$
\begin{gathered}
X \in \mathbb{R}^{7290} \\
\text { Only using } N=100, M=10
\end{gathered}
$$



## How parameters affect the performance



## Future Directions

- Ongoing work: Constrained optimization problem
- How to choose all the parameters?
- Theory for the numerical method.


