A consensus-based global optimization method for high dimensional machine learning problems

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The Model and algorithm

The Model and algorithm

Goal: find $x^* = \operatorname{argmin}_x L(x), L(x)$ is a non-convex function.

For example:
$$L(x) = \frac{1}{n} \sum_{i} l_i(x)$$

Why non-gradient method?

- Gradient is hard to calculate
- Objective function is non-smooth
- Flat local minimum



It is hard for gradient based method to escape from flat local minimum



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Success rate for SGD to find the correct global minimum is 18%

The Model and algorithm



Relax to their weighted average, in the meantime, explore their surrounding environment.

Require $\lambda \sim O(d)$ to guarantee the convergence of the method

Bad for high-dimensional problems

First improvement



 Intuitively, now the diffusivity allows the particles to explore each dimension with different rate, so more possible to find the global minimum.

$$\frac{\operatorname{Previous model}}{\operatorname{Assume} x^* = a \text{ is a constant.}} dX = -\lambda(X - a) dt + \sigma |X - a| dW^j$$

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$$d[(X)_i - (a)_i] = -\lambda[(X)_i - (a)_i] dt + \sigma |X - a| d(W^j)_i$$

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$$d[(X)_i - (a)_i]^2 = -2\lambda \mathbb{E}[(X)_i - (a)_i]^2 dt + \sigma^2 \mathbb{E}[X - a]^2 dt$$

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$$dE[(X)_i - (a)_i]^2 = -2\lambda \mathbb{E}[X - a]^2 - (-2\lambda + \sigma^2 d) \mathbb{E}[X - a]^2$$

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[Carrillo-Choi-Totzeck-Tse, 18]

Mean field limit of the continuous model

$$dX^{j} = -\lambda(X^{j} - \bar{x}^{*}) dt + \sigma \sum_{k=1}^{d} (X^{j} - \bar{x}^{*})_{k} dW_{k}^{j} \vec{e}_{k}$$

$$N \to \infty$$

$$dX = -\lambda(X - X^{*}) dt + \sigma \sum_{i=1}^{d} \vec{e}_{i} (X - X^{*})_{i} dW_{i}$$
with $X^{*} = \frac{\mathbb{E}(Xe^{-\beta L(X)})}{\mathbb{E}(e^{-\beta L(X)})}.$

Theorem: [Carrilo-Jin-Li-Z, 19]

Under some condition on the initial distribution of X and $\lambda, \sigma, X(t) \to \tilde{x}$ exponentially fast and,

$$L(\tilde{x}) \le -\frac{1}{\beta} \log \mathbb{E}e^{-\beta L(X(0))} + \frac{\log 2}{\beta} \le L(x^*) + O(\beta^{-1})$$



Numerical method

A gradient-free optimization method

Goal: find
$$x^* = \operatorname{argmin}_x L(x) = \operatorname{argmin}_x \frac{1}{n} \sum_i l_i(x)$$

Algorithm [Carrillo-Jin-Li-Z-19]

Initially, randomly generate N particles X^j , at each step we randomly update M particles.



- Let X^j move towards X^* and and explore their neighbor at the same time.

$$X^{j} \leftarrow X^{j} - \lambda \gamma (X^{j} - \bar{X}^{*}) + \sigma \sqrt{\gamma} \sum_{i=1}^{d} \vec{e}_{i} \left(X^{j} - \bar{X}^{*} \right)_{i} z_{i}, \quad z_{i} \sim \mathcal{N}(0, 1)$$

The Model and algorithm

Example:



$$L(x) = \frac{1}{d} \sum_{i=1}^{d} \left[(x_i - B)^2 - 10\cos\left(2\pi(x_i - B)\right) + 10 \right] + C$$



Rastrigin function in $\,d=20\,{\rm with}\,\beta=30\,$

	N = 50, M = 40 $\sigma = 5.1$	N = 100, M = 70 $\sigma = 5.1$	N = 200, M = 100 $\sigma = 5.1$
x* = 0, success rate	97%	99%	98%
$\mathbf{x^*} = 0, \frac{1}{d} \mathbb{E} \left[\ x_T^* - x^*\ ^2 \right]$	5.6E-03	5.03E-04	9.71E-04
x [*] = 1, success rate	94%	99%	95%
$\mathbf{x}^* = 1, \frac{1}{d} \mathbb{E} \left[\ x_T^* - x^*\ ^2 \right]$	3.9E-03	4.95E-04	3E-03
x* = 2, success rate	97%	100%	92%
$\mathbf{x^*} = 2, \frac{1}{d} \mathbb{E} \left[\ x_T^* - x^*\ ^2 \right]$	3.0E-03	8.06E-06	4E-03
Computing time saved	22.03%	30.11%	36.14%

TABLE 2. Rastrigin function in d = 20 with $\alpha = 30$.

			N	
x_*		50	100	200
0	success rate	34.%	61.1%	62.2%
	$\frac{1}{d}\mathbb{E}[\ v_f(T) - x_*\ ^2]$	$3.12e^{-1}$	$2.47e^{-1}$	$2.42e^{-1}$
1	success rate	34.5%	57.1%	61.6%
	$\frac{1}{d}\mathbb{E}[\ v_f(T) - x_*\ ^2]$	$3.09e^{-1}$	$2.52e^{-1}$	$0.244e^{-1}$
2	success rate	35.5%	54.8%	62.4%
	$\left \frac{1}{d} \mathbb{E}[\ v_f(T) - x_*\ ^2] \right $	$3.06e^{-1}$	$2.51e^{-1}$	$2.44e^{-1}$

[Pinnau-Totzeck-Tse-Martin, 17]

Learning MNIST data with two layer Neural Network

$$X \in \mathbb{R}^{7290}$$

Only using $N = 100, M = 10$



How parameters affect the performance

Future Directions

- Ongoing work: Constrained optimization problem
- How to choose all the parameters?
- Theory for the numerical method.

